# Micronics U1000MKII-HM

## Clamp On Ultrasonic Heat Meter

**User Manual** 



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## **1** General Description

- Fixed installation, clamp-on heat meter
- Easy to install
- Requires the minimum of information to be entered by the user
- Electronics and guide rail housings form an integral unit
- Attached to the pipe using the supplied jubilee clips
- Power to the unit is provided by an external 12 24V ac/dc power supply (7VA minimum)
- Operates on steel, stainless steel, copper and plastic pipes with IDs in the range 20mm (0.8") to 165mm (6.5") depending on product purchased
- Simple to install temperature sensors
- Compact, rugged and reliable, the U1000MKII-HM has been designed to provide sustained performance in industrial environments

#### U1000MKII HM standard features include:

- 2 line x 16 character LCD with backlight
- 4-key keypad
- Isolated pulse output
- Universal guide rail for setting pre-assembled transducers
- Two sets of self-adhesive Gel pad acoustic couplant
- Dual PT100 type temperature sensors (standard cable length 3m)
- Continuous signal monitoring
- Password protected menu operation for secure use
- Operates from external 12 to 24Vac or dc power supplies
- Small pipe adaptors

#### Options

- Select Pipe range
  - > 20mm inside diameter to 114mm inside diameter pipe
  - > 115mm inside diameter to 165mm inside diameter pipe
- Available as Modbus heatmeter
- Available as Pulse only heat meter

#### Typical applications

- Hot water metering and flow measurement
- Flow measurement for Energy Metering
- Chilled water metering and flow measurement

## 2 Quick Start Procedure

The following procedure details the steps required to set up the heat meter. See the sections referred to if you are unsure about how to install the instrument.

- 1. Wire the electronics up to a 12 to 24V ac or dc power supply (7VA minimum per instrument) via the Blue and Brown wires. (See Section 5.7).
- 2. Establish a suitable location for the flow meter on a straight length of pipe clear of bends and valves or similar obstructions. (See Sections 5 and 5.1).
- 3. Determine the pipe **internal** diameter and material.
- 4. Either use the table in the manual, or power up the instrument to determine the correct separation code. (See Sections 5.2 or 6).
- 5. Set the sensors to the correct separation by adjusting the sensor holding screws so the sensor can slide in the slot. (See Section 5.2).
- 6. Select any adaptors needed for pipes with an **outside** diameter of less than 60mm, **inside** diameter will typically be less than 50mm. (See Section 5.4).
- 7. Apply the Gel pads to the sensors and mount the guide rail on the pipe using the banding provided, then remove the sensor holding screws. (See Section 5.3).
- 8. Plug in the flow and temperature sensors and check that flow and temperature readings can be obtained. (See sections 6 and 7.1). The electronics can be left resting on the guide rail and fully clipped down later once all measurements have been checked.
- 9. Place the temperature sensors touching each other. Wait for the temperature readings to stabilize, indicated by no change for 1 minute. Then zero the temperature sensors. (See Section 5.5).
- 10. Attach the temperature sensors on to the pipe using the self-adhesive pads. Then use the supplied banding to secure the sensor to the pipe. Don't overtighten the banding. The sensor must be in good thermal contact with the pipe and the leads must not be under any strain. (See Section 5.5).
- 11. Once good readings have been obtained any further changes, such as selecting different units, can be made via the User Menu. (See Section 7).
- 12. Clip the electronics assembly on to the guide rail and tighten screw to complete the assembly.
- 13. If the Modbus interface is being used then the address, and data rate, and configuration of the instrument must be set using the User Menu. (See Section 7). The default address is 1, the default data rate is 38400 baud, and the default comms configuration is 8-None-2.

## 3 How Does It Work?

The U1000MKII-HM is a clamp-on, ultrasonic flowmeter that uses a cross correlation transit time algorithm to provide accurate flow measurements.

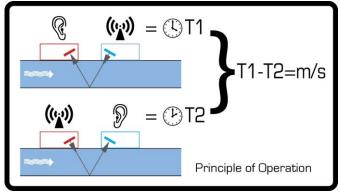


Figure 1 Principle of Transit-Time operation

An ultrasonic beam of a given frequency is generated by applying a repetitive voltage pulse to the transducer crystals. This transmission goes first from the Downstream transducer to the Upstream transducer (red) as shown in the upper half of Figure 1. The transmission is then made in the reverse direction, being sent from the Upstream transducer (red) to the Downstream transducer (blue) as shown in the lower half of Figure1. The speed at which the ultrasound is transmitted through the liquid is accelerated slightly by the velocity of the liquid through the pipe. The subsequent time difference T1 - T2 is directly proportional to the liquid flow velocity.

The two temperature sensors measure the difference in temperature between inlet and outlet of the flow system being monitored. The temperature difference, in combination with the volume of water that has flowed through the system, is then used to calculate the energy transferred to or from the water.

## 4 User Interface

Figure 2 illustrates the U1000MKII-HM user interface comprising:-

- One 2 line x 16 character LCD with backlight
- Four tactile key switches
- Two LEDs





#### 4.1 Key Switches



Selection key. Allows the user to select between options on the display.

Used to decrement the value of each digit in numeric entry fields.

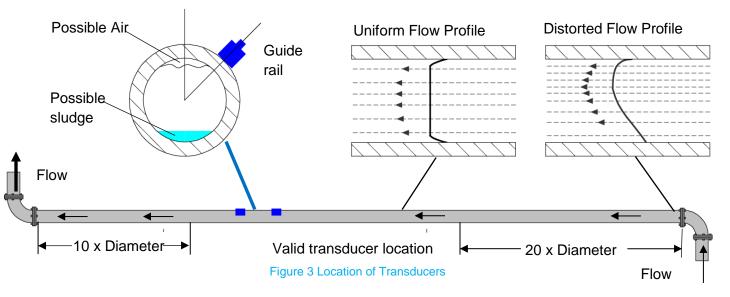
 $\Lambda$  Used to increment the value of each digit in numeric entry fields.

Used to enter the selection displayed or terminate the data entry. Pressing this key can also take the user to a sub menu or to the Flow Reading screen.

kWh LED is illuminated when the Energy pulse is enabled.

Pulse LED is illuminated when the Pulse, Frequency or Alarm functions are eneabled.

## 5 Installing The U1000MKII-HM



For optimum reliability on boiler applications, the flow measurement needs to be made on the cold side of the system. For optimum reliability in chiller applications, the flow measurement needs to be made on the warmer side of the system, making sure sensors are positioned as in figure 3 above.

In many applications an even flow velocity profile over a full 360° is unattainable due, for example, to the presence of air turbulence at the top of the flow and possibly sludge at the bottom of the pipe. Experience has shown that the most consistently accurate results are achieved when the transducer guide rails are mounted at 45° with respect to the top of the pipe.

The U1000MKII-HM equipment expects a uniform flow profile, as a distorted flow will produce unpredictable measurement errors. Flow profile distortions can result from upstream disturbance such as bends, tees, valves, pumps and other similar obstructions. To ensure a uniform profile the transducers must be mounted far enough away from any cause of distortion such that it no longer has an effect.

To obtain the most accurate results the condition of both the liquid and the pipe must be suitable to allow ultrasound transmission along the predetermined path. It is important that liquid flows uniformly within the length of pipe being monitored, and that the flow profile is not distorted by any upstream or downstream obstructions. This is best achieved by ensuring there is a straight length of pipe upstream of the transducers of at least 20 times the pipe diameter, and 10 times the pipe diameter on the downstream side, as shown in Figure 3. Flow Measurements can be made on shorter lengths of straight pipe, down to 10 diameters upstream and 5 diameters downstream, but when the transducers are mounted this close to any obstruction the resulting errors can be unpredictable.

Key Point: Do not expect to obtain accurate results if the transducers are positioned close to any obstruction that distorts the uniformity of the flow profile.

Micronics Ltd accepts no responsibility or liability if product has not been installed in accordance with the installation instructions applicable to the product.

#### 5.1 Preparation

1. Before attaching the transducers, first ensure that the proposed location satisfies the distance requirements shown in Figure 3 otherwise the resulting accuracy of the flow readings may be affected. The unit is preconfigured for the application as follows :-

Instrument TypeHeating or ChillerInstallationFlow or ReturnFluidWater or Water + 30% Ethylene GlycolFlow and Return refer to the location of the Flow measurement relative to flow circuit.Details of this configuration can be found in the Diagnostics menu. (See Section 9).

2. Prepare the pipe by degreasing it and removing any loose material or flaking paint in order to obtain the best possible surface. A smooth contact between pipe surface and the face of the transducers is an important factor in achieving a good ultrasound signal strength and therefore maximum accuracy.

#### 5.2 Sensor Separation

The sensors must be separated by the correct distance for the pipe size and type they will be used on. The table below gives a guide to the typical separation code for a given pipe material and **inside diameter**. If the wall thickness is significantly different from this value then the separation may need to be one code higher or lower. The instrument displays the required separation after the pipe **internal** diameter and material are entered.

Pipe ID	Pipe ID	Water	Glycol
mm	inches	S/Steel	S/Steel
20-22	0.79-0.87	A-3	A-3
26-29	1.02-1.14	B-2	B-2
34-36	1.34-1.42	C-2	C-4
37-40	1.46-1.57	B-3	D-4
52-58	2.05-2.29	B-2	D-3
59-64	2.32-2.52	A-3	F-3
72-79	2.83-3.11	B-3	E-5
86-92	3.39-3.62	C-3	B-4
99-105	3.90-4.13	D-3	C-4
125-131	4.92-5.16	F-3	E-4
152-158	5.98-6.22	E-5	G-4

Pipe ID Pipe ID		Water	Glycol
mm	inches	PVC U	PVC U
22-23	0.87-0.90	C-3	C-3
27-28	1.06-1.10	D-2	C-3
36-37	1.42-1.45	C-4	C-4
43-45	1.69-1.77	C-3	B-4
56-59	2.20-2.32	E-3	E-3
67-69	2.64-2.71	E-4	D-5
78-81	3.07-3.19	D-2	C-3
95-101	3.74-3.97	D-3	C-4
109-115	4.29-4.53	E-3	D-4
122-128	4.80-5.04	F-3	E-4
143-149	5.63-5.87	F-4	E-5
157-162	6.18-6.34	G-4	F-5

PipelD	Pipe ID	Water	Glycol
mm	inches	M/Steel	M/Steel
21-22	0.83-0.87	C-3	C-3
27	1.06	D-2	E-3
35-36	1.38-1.42	C-4	C-4
41-44	1.61-1.73	C-3	F-3
52-54	2.05-2.13	C-4	C-4
62-65	2.44-2.56	F-3	F-3
76-79	2.99-3.11	E-5	G-4
88-94	3.46-3.70	B-4	B-4
95-101	3.74-3.98	D-3	C-4
122-128	4.80-5.04	F-3	E-4
150-156	5.90-6.14	E-5	G-4

Pipe ID	Pipe ID	Water	Glycol
mm inches		Copper	Copper
20-39	0.79-1.54	B-1	B-1
20-39	0.79-1.54	B-1	B-1
20-39	0.79-1.54	B-1	B-1
20-39	0.79-1.54	B-1	A-2
47-53	1.85-2.09	C-1	C-1
61-67	2.40-2.64	A-3	A-3
68-74	2.68-2.91	C-2	B-3
96-102	3.78-4.02	B-4	B-4
117-123	4.61-4.84	E-3	D-4
146-152	5.75-5.98	D-5	D-5

Figure 4 Separation Table

1 Top view as received, See	D C B A D 1 2 3 4 5	
2 Undo screw lowering sensor	3 Lower enough for sideways movement	
5 Sensors in the new positi	D C B A D 1 2 3 4 5	

The diagram below shows how to adjust the separation of the sensors

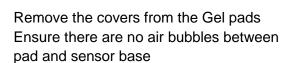
Figure 5 Separation Setting

NOTE. When the sensors have been moved to the correct setting and the guide rail is attached to the pipe REMOVE the sensor holding screws, which will allow the spring loaded transducers to make contact with the pipe.

## 5.3 Attaching the U1000MKII-HM to the pipe

After applying the Gel pads centrally on the sensors, follow the four steps shown in Figure 6 below to attach the U1000MKII-HM to the pipe.







Check separation distance table on page 8 or program unit before clamping guide rail to pipe, using the supplied banding. Then release and REMOVE sensor locking screws.



Connect sensors to the electronics assembly before applying power. Sensor leads can be connected either way round.



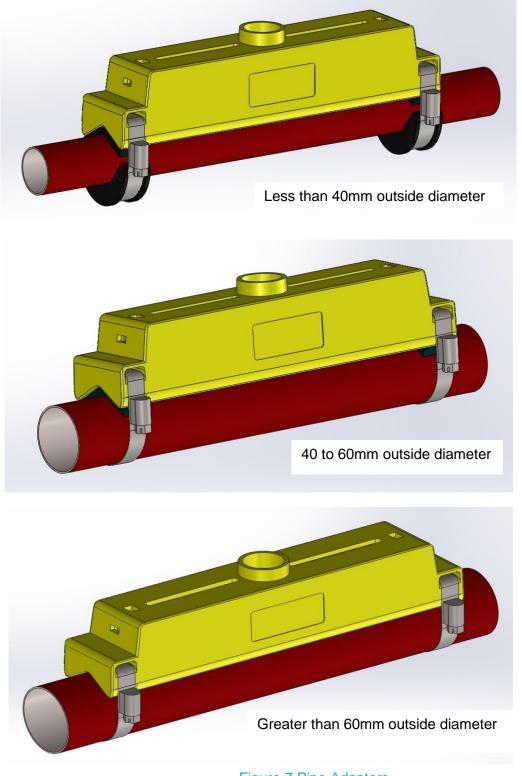
Confirm the unit is working correctly before attaching the electronic assembly onto guide rail assembly.

#### Figure 6 simple steps to attaching the U1000MKII-HM on the pipe

Note...The locking screws and washers should be kept in case it is necessary to change the location of the guide rail and sensors. See the relocation section (section 10) for the procedure to do this.

#### 5.4 Adaptors For Small Pipes

Guide rails for small pipes are supplied with adaptors. The diagram below show how these are fitted around the pipe. The top part of the pipe adaptor clips into the ends of the guide rail.



#### 5.5 Attaching The Temperature Sensors

The temperature sensors must be located at the input and output of the system that is being monitored. The area of pipe where they are to be attached must be free of grease and any insulating material. It is recommended that any coating on the pipe is removed so that the sensor has the best possible thermal contact with the pipe.

The sockets on the enclosure are marked Hot and Cold. This defines the location of the temperature sensors on installations where heat is being extracted from the system.

To ensure an accurate temperature differential the following procedure should be used.

- 1. Plug in the sensors and place them touching each other for 1 minute.
- 2. Enter the password controlled menu (See Section 8) and scroll to the calibration sub-menu.
- 3. Press the Enter key until the Zero Temp Offset screen is displayed.
- 4. Select Yes and press the Enter key to display the Attach Sensors screen.
- 5. Press the Enter key again and wait for instrument to return to the Zero Temp Offset screen.

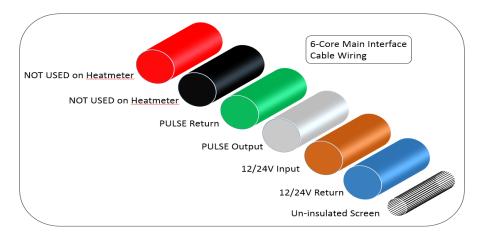
The instrument can now be turned off and the installation of the temperature sensors completed.

The sensors have a cut out profile to locate them; they are then anchored using the supplied cable ties. The cable ties should not be over tightened or the sensors may be damaged. If the sensors are located under pipe lagging then ensure this does not put a strain on the sensor cables. Tie down the sensor cables after the sensors have been installed.

The temperature sensors must be balanced before initial use, using the procedure described above and used with the cable length supplied. Extending or shortening the cables will negate the calibration of the sensors.

#### 5.6 U1000MKII-HM Interface Cables

The U1000MKII-HM interface cable supplied is a 6-core cable for power and pulse output connections and a separate 4 core plug-in cable for the Modbus connections.



The un-insulated wire is the connection to the screen of the cable and should be earthed for full immunity to electrical noise.

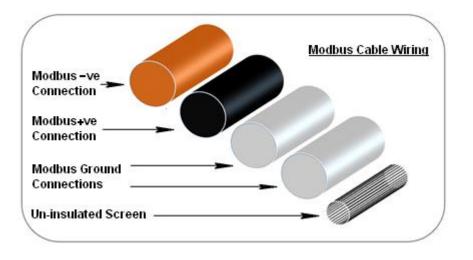


Figure 8 U1000MKII-HM instrument connections

#### 5.7 Connecting The U1000MKII-HM To The Supply

The U1000MKII-HM will operate within the voltage range 12 - 24V ac/dc. The supply must have a minimum rating of 7VA per instrument. Connect the external power supply to the Brown and Blue wires of the six core cable.

For safety, connecting the U1000MKII to a power supply via a mains rated transformer is the responsibility of the installer to conform to the regional voltage safety directives.

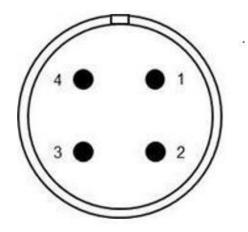
## 5.8 Pulse Output Connection

The isolated pulse output is provided by a SPNO/SPNC MOSFET relay which has a maximum load current of 500mA and maximum load voltage of 48V AC. The relay also provides 2500V isolation, between the sensor's electronics and the outside world.

The pulse output is available at the White and Green wires. Electrically this is a volt, or potential free contact, and when selected as a low flow alarm is configurable NO/NC.

#### 5.9 Modbus Connections

A lead is provided for the Modbus connections that plugs into the electronics assembly near the power cable entry. The Brown is the -ve bus wire and the Black is the +ve bus wire. Both White wires go to ground.



PIN	FUNCTION	COLOUR
1	Modbus -ve	BROWN
2	Modbus ground	WHITE
3	Modbus +ve	BLACK
4	Modbus ground	WHITE

Modbus Connector Cable Part - Binder 99-9210-00-04 (Front View)

For reliable operation of a Modbus network the cable type and installation must comply with requirements in the Modbus specification document "MODBUS over Serial Line Specification & Implementation guide V1.0".

#### 5.10 Cable Screen

For full immunity to electrical interference the screen of the power/pulse output cable and modbus cable should be connected to Earth.

## 6 Powering Up For The First Time

Powering up for the first time will initiate the sequence shown in Figure 10:

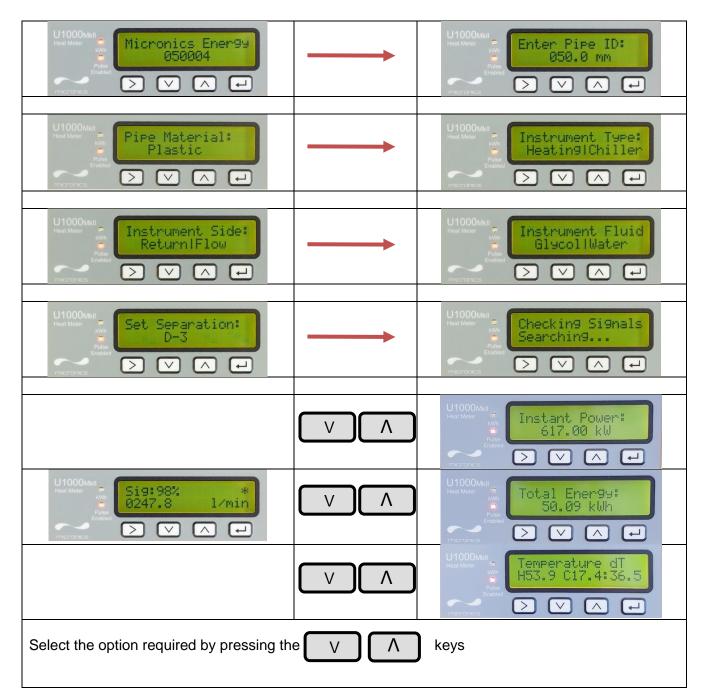


Figure 10 initial power up screens

1. The Micronics start up screen is displayed for 5 seconds.

2. The user enters the pipe ID and selects the material (refer to section 6.1).

3. On pressing Enter in response to the Set Separation screen, the U1000MKII-HM then checks for a valid signal.

4. If a valid signal is found, signal strength and flow rate are displayed. The signal strength should be at least 40% for reliable operation. The direction of flow when powered up will be taken to be the positive flow direction. The pulse output will relate to the flow in this direction. If the flow is reversed then the flow rate will still be displayed but the activity indication will change from an asterisk to an exclamation mark and no pulses will be generated.

If the flow value is displayed as "-----" this indicates that there is no usable signal from sensors. The cause of this could be:

- Incorrect pipe data
- Sensor not in contact with the pipe
- Air in the liquid/pipe

- No Gel pad/grease on the sensor
- Very poor pipe condition-surface/inside

#### Please note:

There is little available data on the specific heat capacity (K factor) for water glycol mixes and there is no practical method of determining the percentage of glycol in a system or the type of glycol in use. The calculations are based on a Water/Ethylene glycol mix of 30%.

In practical terms the results should not be considered more than an approximation as:

The fluid speed of sound can vary between 1480ms and 1578ms

No temperature compensation curve is available for water/glycol mixes,

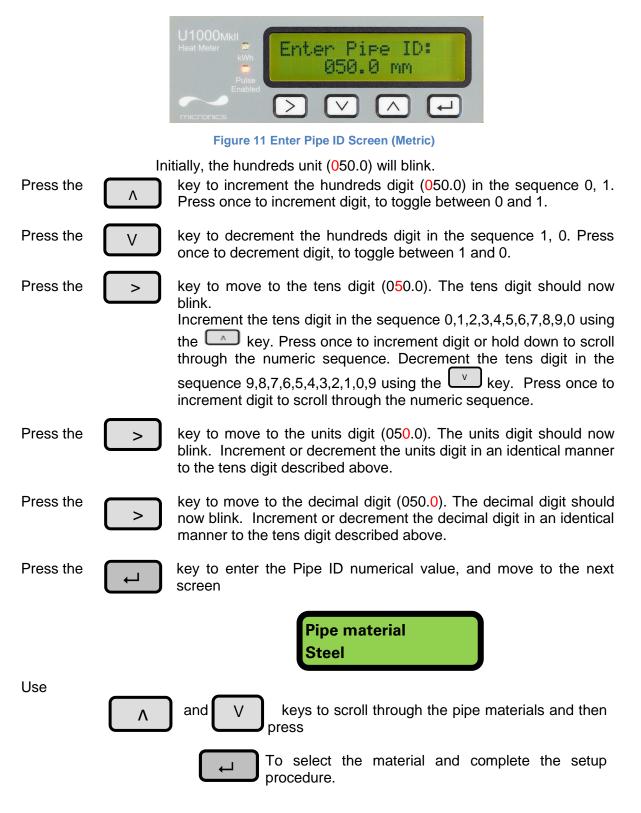
The percentage of Glycol can vary the specific heat capacity from 1.00 to 1.6 J/M<sup>3</sup> \* K

The type of glycol added can change the specific heat capacity and fluid speed of sound considerably.

The Factory enabled user set-up of the application relies on the installer to set the correct operating parameters, a considerable variation in results can be obtained from incorrectly set-up units.

## 6.1 How To Enter The Pipe ID

Figure 11 shows the Enter Pipe ID screen after an initial power up.



If any of the parameters need to be changed from the default values, for example different units are required, then the menu system must be activated via the password (see section 8).

#### 6.2 Pulse Output

Pulse output can be set up to operate in four modes: Volume, Frequency, Energy or Flow Alarm.

#### 6.2.1 Volumetric Mode

In Volumetric mode, each pulse output represents a measured volume of 10 litres (default value). In Volumetric mode, with the Vol per Pulse set to 1 and the pulse width set to 50ms, the maximum number of pulses that can be output (without storage) is  $1/(0.05^{*}2) = 10$  pulses per second. If the flow rate in the pipe is such that it is greater than 10 pulses per second, increase the Vol per Pulse to 10 litres, or reduce the Pulse Width value, to avoid creating a buffer of pulses when the flow stops.

#### 6.2.2 Frequency Mode

In Frequency mode, the pulse output frequency is proportional to the flow rate within a specified frequency range of 1 - 200Hz. The flow units on the frequency output are fixed as litres per second.

The conversion factors from imperial units are:-US gallons/minute multiply by 0.06309 US gallons/hour multiply by 0.00105 Imperial gallons/minute multiply by 0.07577 Imperial gallons/hour multiply by 0.001263

#### 6.2.3 Energy Mode

When the Pulse Output is set to Energy, the kWh LED will be permanently on. Choose from 1,10,100kWh or 1MWh when in metric mode and 1,10,100kBTU or 1MBTU in imperial mode. Each pulse represents an amount of energy e.g. 1kWh. The same limitation on maximum pulse rate applies as detailed in the Volumetric Mode. Again a larger unit of energy per pulse or a smaller pulse width may be required.

#### 6.2.4 Flow Alarm – Low Flow or Signal Loss

It is possible to use the pulse output as a Low Flow Alarm or a Signal Loss Alarm.

For the High/Low Alarm the user can set a range between 0 and 9999 (no decimal places), in the same units being used to measure flow. The default setting is normally open, but the user can select between N/O and N/C. There is a 2.5% hysteresis on the switching of the output. Once turned on the flow rate must rise by 2.5% more than the set value to turn it on/off again.

If the flow reading (Signal) is lost, as indicated by the flow rate being displayed as "-----", the alarm will be triggered. The Pulse LED will indicate the state of the alarm. The default setting is normally open, but the user can select between N/O and N/C.

The Pulse LED will be on if the alarm is set.

#### 6.3 Modbus (if fitted)

The Modbus RTU interface is configured via the Modbus sub menu in the password controlled menu.

The data rate can be selected in the range 1200 to 38400 baud.

The address can be set in the range 1 to 126.

Polling Rate 1000ms (1sec). Time out after 5 seconds.

The instrument responds to the "read holding registers" request (CMD 03).

If the flow reading is invalid then the flow value will be zero.

If a temperature sensor goes out of range then the value will go to -11.

Both of these faults will set the relevant status bit. The following registers are available.

Modbus Register	Register Offset	Туре		Typical Contents		Meaning	Notes
n/a	n/a	Byte		0x01		Instrument Address	
n/a	n/a	Byte		0x03		Instrument Command	
n/a	n/a	Byte		0x40		Number of bytes to read	
40001	0	Int-16		0x00		Device ID	0xAC Energy Meter
				0xac			3, 14
40002	1	Int-16		0x00		Status	0x0000 OK
				0x00			Not[0x0000] Fault
40003	2	Int-16		0x00		System Type	0x04 Heating system
				0x04			0x0C Chiller system
40004	3	Int-16		0x00			
40004	0		0x01				
40005	4	Int-16		0x23		Serial Identifier	
				0x45			
40006	5	Int-16		0x60			
				0x00			
40007	6			0x40			
		iee754		0x1f 0x67 Me	Measured Velocity	Units in m/s	
40008	7			0x67 0xd3			
				0xu3 0x41			
40009	8			0x8c			Units in m3/hr for Metric
		iee754		0xd8		Measured Flow	Units in US Gal/m
40010	9			0xb0			for Imperial
10011	40			0x42			Units in kW for
40011	10	:00754		0x1c		Coloulated Douver	Metric
40012	11	iee754		0x2e		Calculated Power	Units in BTU/s for
40012				0x34			Imperial
40013	12			0x44			Units in kWh for
40013	12	iee754		0x93		Calculated Energy	Metric
40014	13	1001 34		0xc6		Calculated Energy	Units in kBTU for
70017	10			0xe8			Imperial

40015	14		0x41		Units in Degrees Celsius for
		iee754	0x98 0x00	Measured Temperature (Hot)	Metric Units in Degrees
40016	15		0x00 0x00		Fahrenheit for Imperial
			0x00 0x41		
40017	16		0x88		Units in Degrees Celsius for
40018		iee754	0x00	Measured Temperature (Cold)	Metric Units in Degrees Fahrenheit for Imperial
	17		0x00		Famenneit für impenai
10010	40		0x40		
40019	18	100754	0x00	Measured Temperature	Units in Degrees Celsius for
40020	19	iee754	0x00	(Difference)	Metric Units in Degrees Fahrenheit for Imperial
40020	19		0x00		
40021	20		0x60		
10021	20	iee754	0xef	Measured Total	Units in m3 for Metric
40022	21	1667.04	0x3c		Units in US Gal for Imperial
			0x1c		
40023	22	Int-16	<u>0x00</u>	Instrument Units	0x00 Metric
			0x00		0x01 Imperial
40024	23	Int-16	0x00	Instrument Gain	Gain in dB
	24	Int-16	0x01 0x00	Instrument SNR	SNR in dB
40025			0x00 0x0a		
	25		0x00	Instrument Signal	Signal in %
40026		Int-16	0x62		
40007			0x42		
40027	26	100754	0xc9	Measured Delta-Time	Diagnostic Data
40028	27	iee754	0xff	Difference	Units in nanoseconds
40020	21		0x7d		
40029	28		0x42		
40029	20	iee754	0xa8	Instrument ETA	Diagnostic Data
40030	29	166134	0x8b		Units in nanoseconds
-+0000	23		0xf5		
40031	30		0x42		
		iee754	<u>0xc8</u>	Instrument ATA	Diagnostic Data
40032	31	100704	0x00		Units in nanoseconds
			0x00		
n/a	n/a	Int-16	0xed	CRC-16	
		-	0x98		

On a unit set to Imperial the temperature is in °F, Power is in BTUs and flow in US Gallons.

#### Figure 12 Modbus registers

## 7 Subsequent Power-ON Sequence

If the power supply is cycled OFF then ON after the pipe data has been entered, all subsequent start-ups will use the same configuration as was previously entered. If the configuration needs to be changed for any reason, the user can make use of the password-controlled menu as described in section 7.

## 8 Information Screens

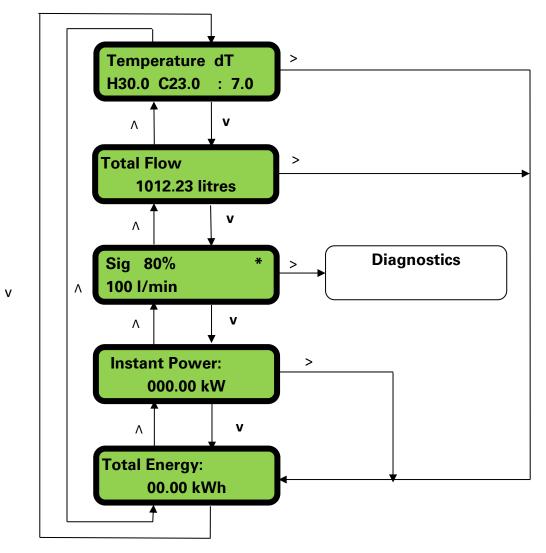


Figure 13 information screens

The system will initially display the Flow Reading screen. If there are valid flow and temperature readings, then after a few seconds the Total Energy screen will be displayed.

If the flow reading is invalid then the Flow screen will be displayed. Similarly the Temperature screen will be displayed if a reading goes out of range.

## 9 Password Controlled Menus

The password controlled menu allows the user some flexibility to change the default settings:

	•					
User Password (71360):						
Setup Menu						
•	Comms Menu					
•	Pulse Output Menu					
•	Calibration Menu					
•	Totaliser Menu					

## 9.1 General Procedure For Changing Menu Settings

#### 9.1.1 Selection Menus

When a password controlled menu is selected the procedure for changing the default setting is the same for most menus. For example, consider the Flow Units menu shown in Figure 14.



Figure 14 Flow Units menu

The default value 'I/min' will blink to indicate that this is the current setting. To change to 'I/s', press the key. Now the 'I/s' units will blink to indicate that this is now the selected units. Press the key to confirm the change.

There are other default settings where the  $\land$  and  $\lor$  keys are used to scroll through the options.

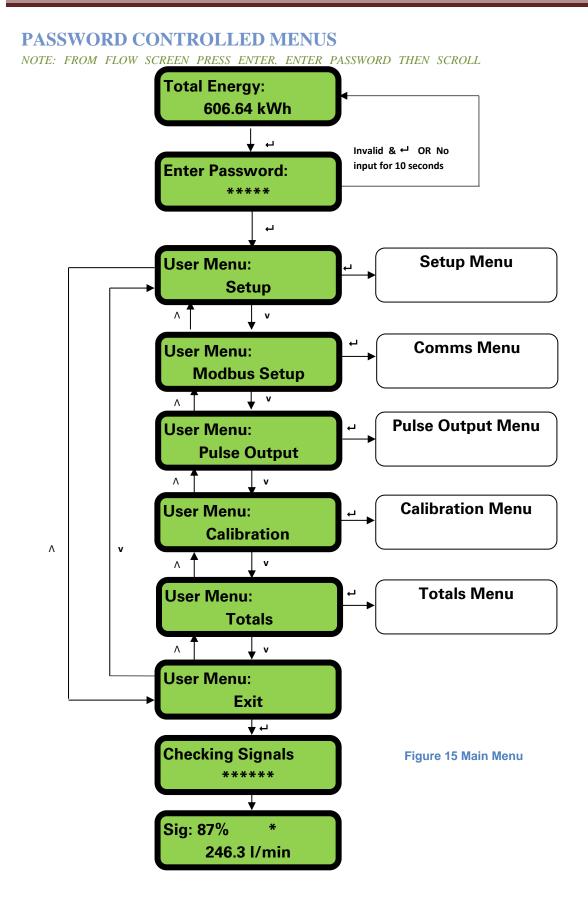
## 9.1.2 Data Entry Menus

Menus containing a numeric value can be altered using the same method used to input the pipe ID.

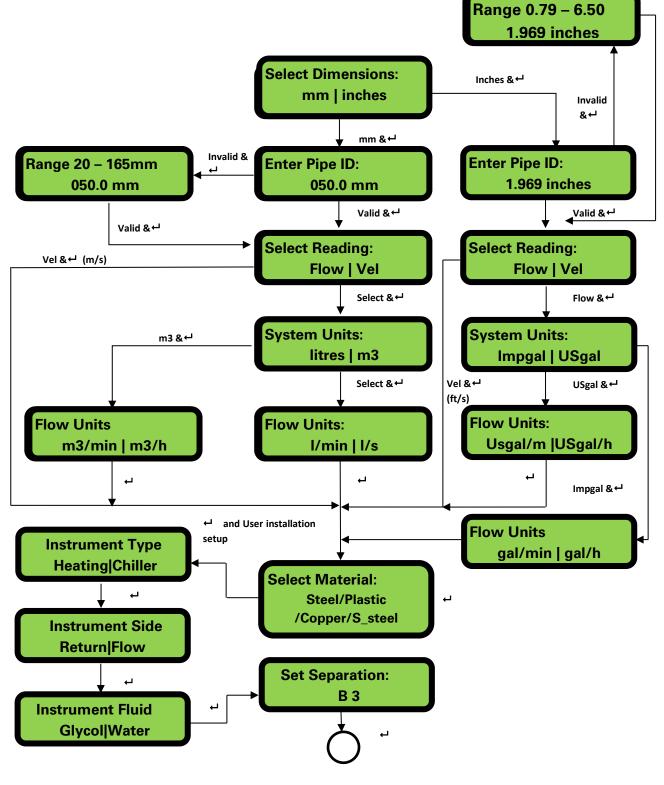
#### 9.2 User Password Controlled Menu Structure

While in Flow reading or Total flow mode, pressing the *Led* key will access the user password menu. Enter 71360 using the procedure explained in section 6.1 to enter the password.

The flow chart shown in Fig.15 shows the user password menu structure. To skip over any menu item that should remain unchanged, simply press the key.



#### **SETUP MENU**



#### Figure 16 Setup Menu

If "inches" is selected then the temperatures will be displayed in °F and the energy values will be in BTUs.

#### **MODBUS SETUP MENU**

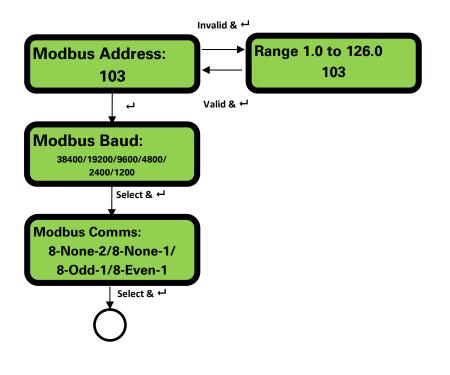


Figure 17 Modbus menu

#### **PULSE OUTPUT MENU**

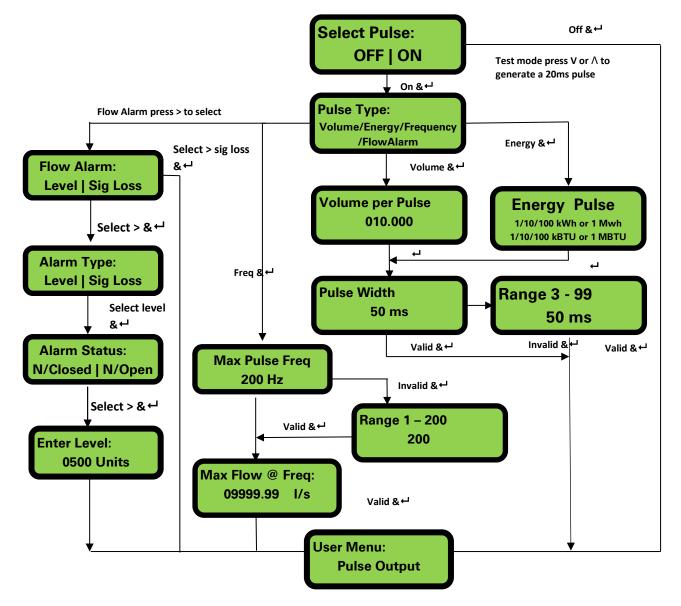
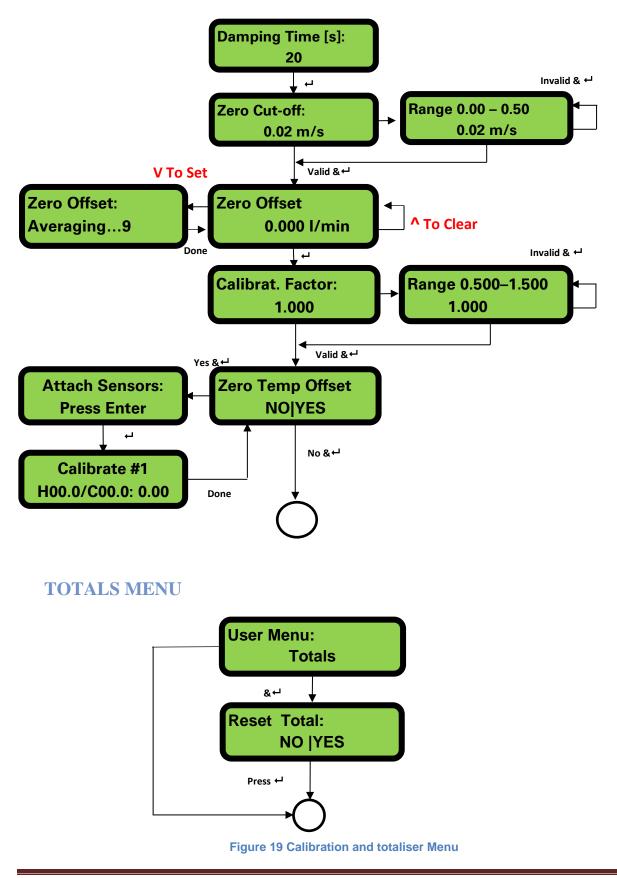


Figure 18 Pulse output

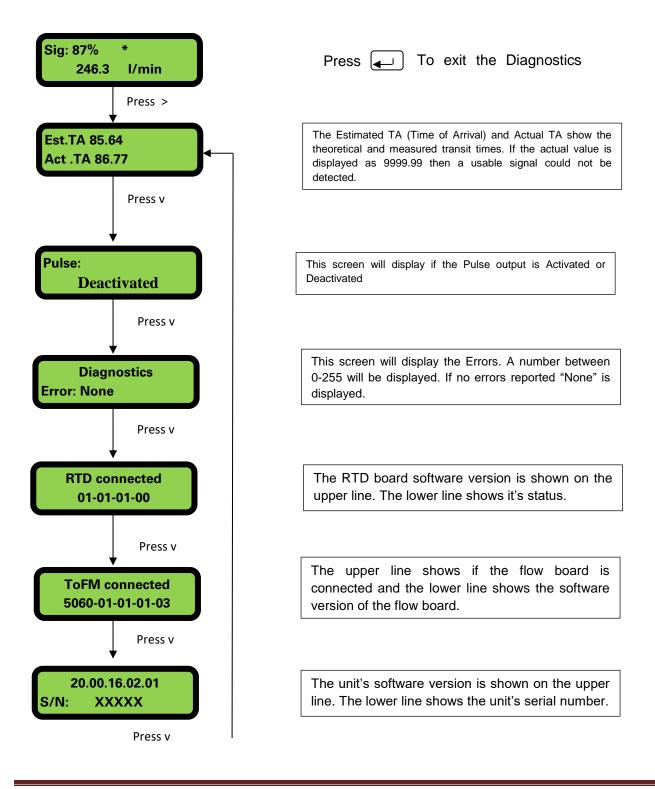
## **CALIBRATION MENU**



## **10 Diagnostics Menu**

The diagnostics menu provides some additional information about the heat meter and its setup. The menu can be accessed by pressing the  $\searrow$  key from flow reading screen. The menu shown below describes the various diagnostics items.

#### **DIAGNOSTICS MENU**





Gain – a decibel number between -5dB and 80dB - lower is better, should be around 40dB or below. Above 60dB need to question the installation. Signal/Noise ratio in dB, scale is 0 to 80dB - higher is better. Below 20 question the installation.

The lower line shows the current time differential between the upstream and downstream signals.

Press 🖵 To exit the Diagnostics

Figure 20 Diagnostics Menu

## 11 Relocation Of Guide Rail

If it is necessary to relocate the guide rail and sensor assembly use the following procedure.

- 1. Remove complete assembly from the pipe.
- 2. Undo the screw at the end of the guide rail and gently lift the same end as shown.
- 3. The opposite end of the electronics can now be released from the guide rail.



Figure 21

- 4. Disconnect the sensors.
- 5. Remove the original Gel pads from the sensors.
- 6. Push the sensor blocks into the guide rail to enable the washers and locking screws to be refitted.
- 7. Replace the Gel pads. A spare set is supplied with the unit and further sets are available from Micronics Ltd.
- 8. Follow the original procedure for installing the guide rail on the pipe.

## 12 Appendix I – U1000MKII-HM Specification

Table 1 lists the U1000MKII-HM Product Specification.

General	
Measuring Technique	Transit time
Measurement channels	1
Timing Resolution	±50ps
Turn down ratio	200:1
Flow velocity range	0.1 to 10m/s bidirectional
Applicable Fluid types	Clean water with < 3% by volume of particulate content, or up to
	30% ethylene glycol
Accuracy	±3% of flow reading for flow velocity >0.3m/s
Repeatability	±0.15% of measured value
Selectable units for Metric (mm)	Velocity: m/s,
	Flow Rate: I/s, I/min, m <sup>3</sup> /min, m <sup>3</sup> /hr
	Volume: litres, m3,
	Energy : kWh, MWh
Selectable units for Imperial (inches)	Velocity: ft/s
	Flow rate: Imp.gal/min, Imp.gal/hr, USgal/min, USgal/hr
	Volume: Imp.gals, USgals
Totaliser	Energy : kBTU, MBTU
	14 digits with roll over to zero
Languages supported	English only
Power input	12 - 24V ac or dc (Isolated)
Power consumption	7VA maximum
Cable	5m screened 6 core
Pulse Output	
Output	Opto-isolated MOSFET volt free NO/NC contact selectable.
Isolation	2500V
Pulse width	Default value 50ms; programmable range 3 – 99ms
Pulse repetition rate	Up to 166 pulses/sec (depending on pulse width)
Frequency mode	200 Hz maximum (1-200)
Maximum load voltage/current	48V AC / 500mA
Modbus	
Format	RTU
Baud rate	1200, 2400, 4800, 9600, 19200, 38400
Data -Parity-Stop Bits	8-None-2, 8-None-1, 8-Odd-2, 8-Even-1
Standards	PI–MBUS–300 Rev. J
Physical connection	RS485

Temperature sensors					
Туре	PT100 Class B 4 wire				
Range	2 to 85°C (36 to 185°F)				
Resolution	0.1°C (32.18°F)				
Minimum delta T	0.3°C (32.54°F)				
Enclosure					
Material	Plastic Polycarbonate				
Fixing	Pipe mountable				
Degree of Protection	IP54				
Flammability Rating	UL94 V-0				
Dimensions	250mm x 48mm x 90mm (electronics + guide rail)				
Weight	0.5kg				
Environmental					
Pipe temperature	0°C to 85°C				
Operating temperature	0°C to 50°C				
(Electronics)					
Storage temperature	-10°C to 60°C				
Humidity	90% RH at 50°C Max				
Display					
LCD	2 line x 16 characters				
Viewing angle	Min 30°				
Active area	58mm (W) x 11mm(H)				
Keypad					
Format	4 key tactile feedback membrane keypad				

Table 1 (cont.) U1000MKII-HM Product Specification.

## 13 Appendix II – Default Values

The settings will be configured at the factory for either metric or imperial units.

Parameter	Default Value	Parameter	Default Value
Dimensions	mm	Calibration Factor	1.000
Flow Rate	I / min	Zero Cut-off	0.02 m / s
Pipe ID	50 (mm)	Zero Offset	0.000 I / min
Pulse Output	Off	Modbus Address	1
Energy per Pulse	1kWh	Data Rate	38400 baud
Pulse Width	50ms	Parity	None
Damping	20s	Stop Bits	2

#### Table 2 System Default Values (Metric)

Parameter	Default Value	Parameter	Default Value
Dimensions	Inches	Calibration Factor	1.000
Flow Rate	USgal / min	Zero Cut-off	0.07 f / s
Pipe ID	1.969 (inches)	Zero Offset	0.000 USgal / min
Pulse Output	Off	Modbus Address	1
Energy per Pulse	1kBTU	Data Rate	38400 baud
Pulse Width	50ms	Parity	None
Damping	20s	Stop Bits	2

Table 3 System Default Values (Imperial)

## 14 Appendix III – Error and Warning Messages

## **Error Messages**

Error Messages are displayed as a number in the diagnostics menu. Contact Micronics if other messages appear.

				Statu	s Byte		1		
Error Meaning		Bit#6	Bit#5	Bit#4	Bit#3	Bit#2	Bit#1	Bit#0	
RTD I2C failed								1	
RTD Thot failed							1		
RTD Tcold failed						1			
TOFM signal lost					1				
TOFM board failed				1					
TOFM window failed			1						
TOFM sensor type falied		1							
TOFM I2C failed									
Examples - Meaning									text displayed
Fully functioning instrument	0	0	0	0	0	0	0	0	None
No ultrasonic signal	0	0	0	0	1	0	0	0	8
Both temperature probes either failed or not plugged in	0	0	0	0	0	1	1	0	6
TOFM I2C failed and hot temperature probe not plugged in	1	0	0	0	0	0	1	0	130
Fully failed instrument	1	1	1	1	1	1	1	1	255

Common Error Message					
Error Message	Error Meaning				
None or 0	None				
2	Hot sensor error				
4	Cold sensor error				
6	Hot and Cold sensor error				
8	No flow signal				
10	Hot error and no flow signal				
12	Cold error and no flow signal				
14	Hot and Cold error no flow signal				

## Modbus Error Messages (if modbus fitted)

	Transmitter								
Test case	Address	Command				n (no of sters)	CRC-16		
	[1 byte]	[1 byte]			[2 bytes]		[2 bytes]		
No error	0x01	0x03	0x00	0x00	0x00	0x20	0x44	0x12	
Incorrect function request	0x01	0x0C	0x00	0x00	0x00	0x20	0x10	0x13	
incorrect register start	0x01	0x03	0x00	0xEF	0x00	0x20	0x75	0xE7	
Incorrect register length	0x01	0x03	0x00	0x12	0xFF	0x02	0x25	0xFE	
slave is busy	0x01	0x03	0x00	0x00	0x00	0x20	0x44	0x12	
incorrect CRC-16	0x01	0x03	0x00	0x20	0x00	0x20	0x44	0xFF	

	F	Reciever			
Address	Command	Error code	CRC-16 [2 bytes]		Comments
[1 byte]	[1 byte]	[1 byte]			
0x01	0x03	None	n/a	n/a	Example of a good message
0x01	0x8C	0x01	0x85	0x00	The only acceptable commands are 0x03 and 0x06
0x01	0x83	0x02	0xC0 0xF1		Incorrrect register start
0x01	0x83	0x03	0x01	0x31	Incorrect register length
0x01	0x83	0x06	0xC1	0x32	slave is busy processing and is unable to respond
0x01	0x83	0x07	0x00	0xF2	CRC is incorrect

## Flow and temperature errors

A signal strength of less than 40% indicates poor set up of the instrument, and the installation should be checked or possibly moved to a different site.

If instant Power is zero, there will either be no flow or flow signal to the flow transducers or the delta T is negative. If this happens check the following.

- 1. Make sure the temperature sensors are connected and securely on the pipe.
- 2. Check the display to make sure there is a deta T.
- 3. Make sure there is flow in the pipe.
- 4. Check the display to make sure flow signal is not showing "----". If so makes sure flow sensors are sitting on the pipe, and check for grease or gel pads have been used.

## Warnings

These generally advise the user that the data entered is out of the specified range.

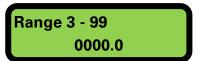
1. When an invalid Pipe ID is entered, the warning message shown below is displayed, prompting the user to enter a value between 20 and 165.1mm, depending on the unit purchased.



2. When programming a Frequency Pulse output the frequency is limited to the range 1 to 200 Hz. If an invalid value is entered then the following warning message is displayed.



3. When programming a Volume Pulse output the pulse width is limited to the range 3 to 99ms. If an invalid value is entered then the following warning message is displayed.



4. When programming the Zero Cut-off this is limited to the range 0.000 to 0.500. If an invalid value is entered then the following warning message is displayed.



5. When programming the Calibration Factor this is limited to the range 0.5 to 1.5. If an invalid value is entered then the following warning message is displayed.



6. If an attempt is made to zero the offset between the temperature sensors, and the difference in temperature is too large then this error message will be displayed.



Ensure the temperature sensors are correctly plugged in and are both at the same temperature.

Updates

25/7/18

Page 13

For safety, connecting the U1000MKII to a power supply via a mains rated transformer is the responsibility of the installer to conform to the regional voltage safety directives.



## EU Declaration of Conformity Micronics Ltd

Knaves Beech Business Centre Davies Way, Loudwater, High Wycombe, Bucks. HP10 9QR

## The Products Covered by this Declaration

This product is manufactured in accordance with the following Directives and Standards.

Directive 2014/30/EU of the European Parliament and of the Council of 26 February 2014 on the approximation of the laws of the Member States relating to electromagnetic compatibility

Directive 2014/35/EU of the European Parliament and of the Council of 26 February 2014 on the harmonisation of the laws of Member States relating to electrical equipment designed for use within certain voltage limits

#### The Basis on which Conformity is being Declared

The manufacturer hereby declares under his sole responsibility that the products identified above comply with the protection requirements of the EMC directive and with the principal elements of the safety objectives of the Low Voltage Equipment directive, and that the following standards have been applied:

BS EN 61010-1:2010 Safety requirement for electrical equipment for measurement control and laboratory use. Part 1 General requirements

BS EN61326-1:2013 Electrical equipment for measurement control and laboratory use EMC requirements. Part 1: General requirements

BS EN61326-2-3:2013 Electrical equipment for measurement control and laboratory use EMC requirements. Part 2-3: Particular requirements – Test configuration and performance criteria for transducers with integrated or remote signal conditioning.

This declaration of conformity is issued under the sole responsibility of the manufacturer. **Signed for and on behalf of : Micronics Ltd.** 

	$\mathcal{N}$		
Signature:	0		
Printed Name:	Michael Farno	n	
Title:	Managing Dire	ector	
Date:	April 2018	Location:	Loudwater
C		Att	ention!
The attention of the spe			special measures and limitations to use which must be observed when aintain compliance with the above directives.
Details of these sp	pecial measures and lim	itations to use are av	ilable on request, and are also contained in the product manuals.
Register	ed Office: Micronics Limite	d, Knaves Beech Busines	s Centre, Davies Way, Loudwater, Buckinghamshire, HP10 9QR
	Webs	site: www.micronicsflowm	eters.com Tel: +44 (1628) 810456
	D	lirectors: E.J. Farnon, E. F	amon, M.A. Famon, D.B. Leigh
	Registra	ation No. 1289680	V.A.T. Registration No. 303 6190 91